1. General description

The HEF4013B is a dual D-type flip-flop that features independent set-direct input (SD), clear-direct input (CD), clock input (CP) and outputs (Q, \overline{Q}) . Data is accepted when CP is LOW and is transferred to the output on the positive-going edge of the clock. The active HIGH asynchronous CD and SD inputs are independent and override the D or CP inputs. The outputs are buffered for best system performance. The clock input's Schmitt-trigger action makes the circuit highly tolerant of slower clock rise and fall times.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD}, V_{SS}, or another input. The device is suitable for use over both the industrial (–40 °C to +85 °C) and automotive (–40 °C to +125 °C) temperature ranges.

2. Features and benefits

- Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Operates across the automotive temperature range from -40 °C to +125 °C
- Complies with JEDEC standard JESD 13-B

3. Applications

- Automotive and industrial
- Counters and dividers
- Registers
- Toggle flip-flops

4. Ordering information

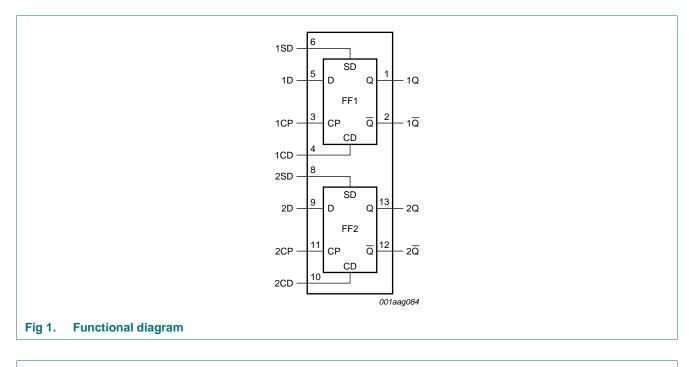
Table 1.Ordering information

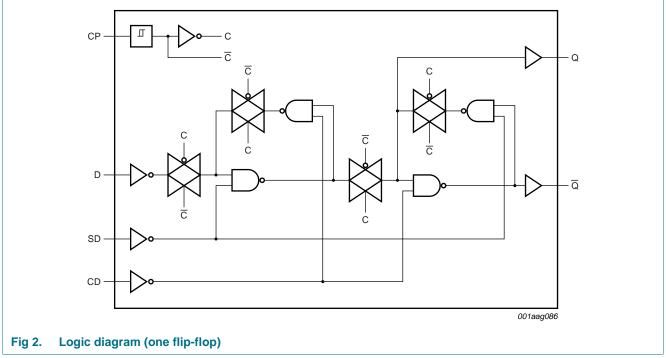
All types operate from -40 °C to +125 °C

Type number	Package		
Name		Description	Version
HEF4013BP	DIP14	plastic dual in-line package; 14 leads (300 mil)	SOT27-1
HEF4013BT	SO14	plastic small outline package; 14 leads; body width 3.9 mm	SOT108-1
HEF4013BTT	TSSOP14	plastic thin shrink small outline package; 14 leads; body width 4.4 mm	SOT402-1



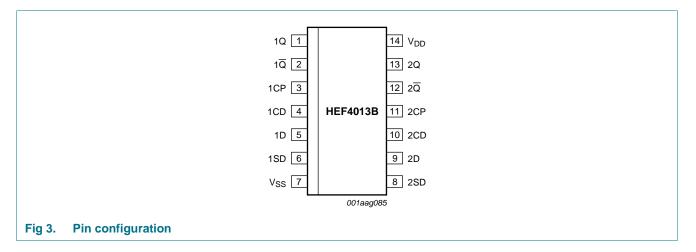
5. Functional diagram





6. Pinning information

6.1 Pinning



6.2 Pin description

Table 2.	Pin description	
Symbol	Pin	Description
1Q, 2Q	1, 13	true output
1 <u>Q</u> , 2 <u>Q</u>	2, 12	complement output
1CP, 2CP	3, 11	clock input (LOW to HIGH edge-triggered)
1CD, 2CD	9 4, 10	asynchronous clear-direct input (active HIGH)
1D, 2D	5, 9	data input
1SD, 2SD	6, 8	asynchronous set-direct input (active HIGH)
V _{SS}	7	ground (0 V)
V_{DD}	14	supply voltage

7. Functional description

Table 3.Function table^[1]

Control			Input	Output		
nSD	nCD	nCP	nD	nQ	nQ	
Н	L	Х	Х	Н	L	
L	Н	Х	Х	L	Н	
Н	Н	Х	Х	Н	Н	
L	L	↑	L	L	Н	
L	L	↑	Н	Н	L	

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; $\uparrow = LOW$ -to-HIGH clock transition.

HEF4013B Product data sheet

8. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to $V_{SS} = 0 V$ (ground).

Symbol	Parameter	Conditions	Min	Max	Unit
V _{DD}	supply voltage		-0.5	+18	V
I _{IK}	input clamping current	$V_{I} < -0.5$ V or $V_{I} > V_{DD}$ + 0.5 V	-	±10	mA
VI	input voltage		-0.5	V _{DD} + 0.5	V
I _{OK}	output clamping current	$V_{\rm O}$ < –0.5 V or $V_{\rm O}$ > $V_{\rm DD}$ + 0.5 V	-	±10	mA
I _{I/O}	input/output current		-	±10	mA
I _{DD}	supply current		-	50	mA
T _{stg}	storage temperature		-65	+150	°C
T _{amb}	ambient temperature		-40	+125	°C
P _{tot}	total power dissipation	$T_{amb} = -40 \ ^{\circ}C \ to \ +125 \ ^{\circ}C$			
		DIP14	<u>[1]</u> -	750	mW
		SO14	[2] _	500	mW
		TSSOP14	[3] _	500	mW
Р	power dissipation	per output	-	100	mW

[1] For DIP14 packages: above T_{amb} = 70 °C, P_{tot} derates linearly with 12 mW/K.

[2] For SO14 packages: above $T_{amb} = 70 \text{ °C}$, P_{tot} derates linearly with 8 mW/K.

[3] For TSSOP14 packages: above $T_{amb} = 60 \text{ °C}$, P_{tot} derates linearly with 5.5 mW/K.

9. Recommended operating conditions

Table 5. Recommended operating conditions

	1 0				
Symbol	Parameter	Conditions	Min	Max	Unit
V _{DD}	supply voltage		3	15	V
VI	input voltage		0	V_{DD}	V
T _{amb}	ambient temperature		-40	+125	°C
$\Delta t / \Delta V$	input transition rise and fall rate	$V_{DD} = 5 V$	-	3.75	μs/V
		V _{DD} = 10 V	-	0.5	μs/V
		V _{DD} = 15 V	-	0.08	μs/V

10. Static characteristics

Table 6. Static characteristics

 $V_{SS} = 0$ V; $V_l = V_{SS}$ or V_{DD} ; unless otherwise specified.

Symbol Parameter		Conditions	V _{DD}	T _{amb} =	−40 °C	T _{amb} =	+25 °C	T _{amb} =	+85 °C	T _{amb} = ·	+125 °C	Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
V _{IH} HIGH-level	I _O < 1 μA	5 V	3.5	-	3.5	-	3.5	-	3.5	-	V	
	input voltage		10 V	7.0	-	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	11.0	-	V
V _{IL}	LOW-level	$ I_0 < 1 \ \mu A$	5 V	-	1.5	-	1.5	-	1.5	-	1.5	V
	input voltage		10 V	-	3.0	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	-	4.0	V
V _{OH}	HIGH-level	$ I_0 < 1 \ \mu A$	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
	output voltage	tput voltage	10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
V _{OL}	LOW-level		5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
	output voltage		10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
I _{OH}	HIGH-level	$V_{O} = 2.5 V$	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mA
	output current	$V_{O} = 4.6 V$	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mA
		$V_{O} = 9.5 V$	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mA
		V _O = 13.5 V	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mA
l _{OL}	LOW-level	$V_{O} = 0.4 V$	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mA
	output current	$V_{O} = 0.5 V$	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mA
		V _O = 1.5 V	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mA
I	input leakage current		15 V	-	±0.1	-	±0.1	-	±1.0	-	±1.0	μΑ
I _{DD}	supply current	all valid input	5 V	-	1.0	-	1.0	-	30	-	30	μΑ
		combinations; $ I_0 = 0 A$	10 V	-	2.0	-	2.0	-	60	-	60	μΑ
			15 V	-	4.0	-	4.0	-	120	-	120	μΑ
CI	input capacitance		-	-	-	-	7.5	-	-	-	-	pF

11. Dynamic characteristics

Table 7. Dynamic characteristics

 $T_{amb} = 25 \ ^{\circ}C$; unless otherwise specified. For test circuit see <u>Figure 6</u>.

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula	a Min	Тур	Мах	Unit
t _{PHL}	HIGH to LOW	nCP to nQ, n \overline{Q} ;	5 V	11 83 + 0.55 \times C _L	-	110	220	ns
	propagation delay	see Figure 4	10 V	$34 \textbf{+} 0.23 \times C_L$	-	45	90	ns
			15 V	$22 \textbf{+} 0.16 \times C_L$	-	30	60	ns
		nSD to nQ	5 V	1 73 + 0.55 \times C _L	-	100	200	ns
			10 V	$29 \textbf{+} 0.23 \times C_L$	-	40	80	ns
			15 V	$22 \textbf{+} 0.16 \times C_L$	-	30	60	ns
		nCD to nQ	5 V	11 73 + 0.55 \times C _L	-	100	200	ns
			10 V	$29 \textbf{+} 0.23 \times C_L$	-	40	80	ns
			15 V	$22 \textbf{+} 0.16 \times C_L$	-	30	60	ns
PLH	LOW to HIGH		5 V	[1] 68 + 0.55 \times C _L	-	95	190	ns
	propagation delay		10 V	$29 \textbf{+} 0.23 \times C_L$	-	40	80	ns
			15 V	$22 \textbf{+} 0.16 \times C_L$	-	30	60	ns
		nSD to nQ	5 V	[1] $48 + 0.55 \times C_L$	-	75	150	ns
			10 V	$24 \textbf{+} 0.23 \times C_L$	-	35	70	ns
		15 V	$17 + 0.16 \times C_L$	-	25	50	ns	
	nCD to nQ	5 V	[1] $33 + 0.55 \times C_L$	-	60	120	ns	
			10 V	$19 \pm 0.23 \times C_L$	-	30	60	ns
			15 V	$12 \pm 0.16 \times C_L$	-	20	40	ns
t	transition time	see Figure 4	5 V	10 + 1.00 × C_L	-	60	120	ns
			10 V	$9 \textbf{+} 0.42 \times C_L$	-	30	60	ns
			15 V	$6 \textbf{+} 0.28 \times C_L$	-	20	40	ns
su	set-up time	nD to nCP;	5 V		40	20	-	ns
		see Figure 4	10 V		25	10	-	ns
			15 V		15	5	-	ns
ĥ	hold time	nD to nCP;	5 V		20	0	-	ns
		see Figure 4	10 V		20	0	-	ns
			15 V		15	0	-	ns
W	pulse width	nCP input LOW;	5 V		60	30	-	ns
		see Figure 4	10 V		30	15	-	ns
			15 V		20	10	-	ns
		nSD input HIGH;	5 V		50	25	-	ns
		see Figure 5	10 V		24	12	-	ns
			15 V		20	10	-	ns
		nCD input HIGH;	5 V		50	25	-	ns
		see Figure 5	10 V		24	12	-	ns
			15 V		20	10	-	ns

Dual D-type flip-flop

$I_{amb} = 28$	5 °C; unless otherwis	se specified. For test	circuit see <u>Fig</u>	<u>ure 6</u> .				
Symbol	Parameter	Conditions	V _{DD}	Extrapolation formula	Min	Тур	Max	Unit
t _{rec} recovery time	nSD input;	5 V		+15	-5	-	ns	
		see <u>Figure 5</u>	10 V		15	0	-	ns
			15 V		15	0	-	ns
		nCD input;	5 V		40	25	-	ns
		see <u>Figure 5</u>	see Figure 5 10 V		25	10	-	ns
			15 V		25	10	-	ns
f _{clk(max)}	maximum clock	see Figure 4	5 V		7	14	-	MHz
	frequency		10 V		14	28	-	MHz
			15 V		20	40	-	MHz

Table 7. Dynamic characteristics ... continued

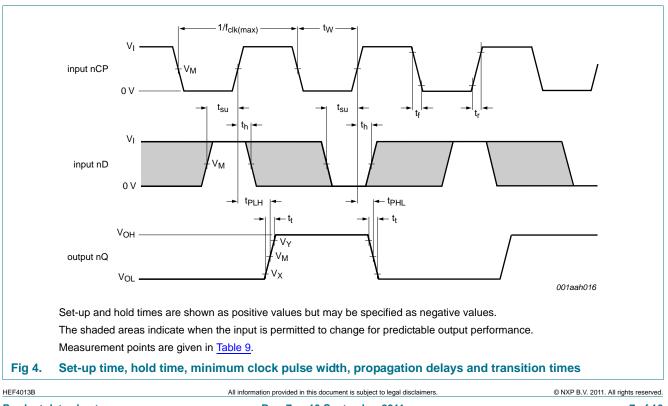
[1] Typical values of the propagation delays and output transition times can be calculated with the extrapolation formulas. CL is given in pF.

Table 8. **Dynamic power dissipation**

 $V_{SS} = 0 V; t_r = t_f \le 20 ns; T_{amb} = 25 \ ^{\circ}C.$

Symbol	Parameter	\mathbf{V}_{DD}	Typical formula	Where
PD	dynamic power dissipation	5 V	$\textbf{P}_{D} = 850 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2} \ \mu \textbf{W}$	f _i = input frequency in MHz;
		10 V	$P_D = 3600 \times f_i + \Sigma(f_o \times C_L) \times V_DD{}^2 \; \muW$	$f_o = output frequency in MHz;$
		15 V	$P_D = 9000 \times f_i + \Sigma(f_o \times C_L) \times V_DD^2 \ \mu W$	C_L = output load capacitance in pF;
				$\Sigma(f_o \times C_L)$ = sum of the outputs;
				V_{DD} = supply voltage in V.

12. Waveforms



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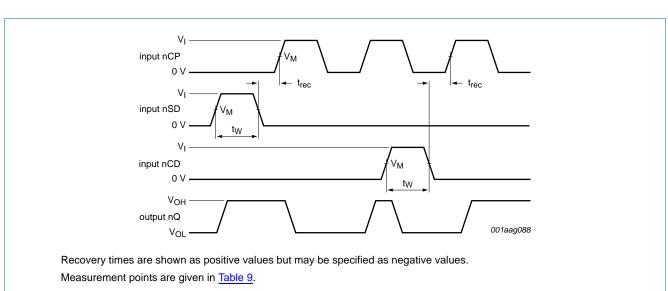


Fig 5. nSD, nCD recovery time and pulse width

Table 9. Measurement points

Supply voltage	Input	Output		
V _{DD}	V _M	V _M	V _X	V _Y
5 V to 15 V	0.5V _{DD}	0.5V _{DD}	0.1V _{DD}	0.9V _{DD}

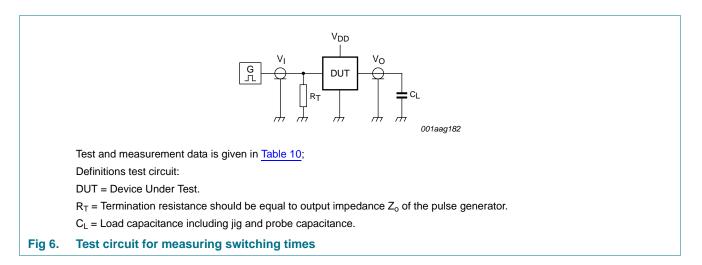


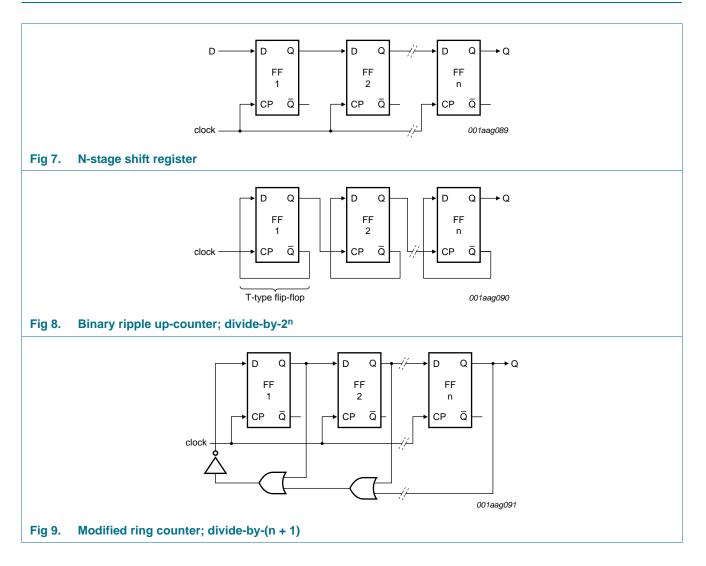
Table 10. Test data

Supply voltage	Input	Input		
V _{DD}	VI	V _I t _r , t _f		
5 V to 15 V	V_{SS} or V_{DD}	\leq 20 ns	50 pF	

HEF4013B Product data sheet **HEF4013B**

Dual D-type flip-flop

13. Application information



14. Package outline

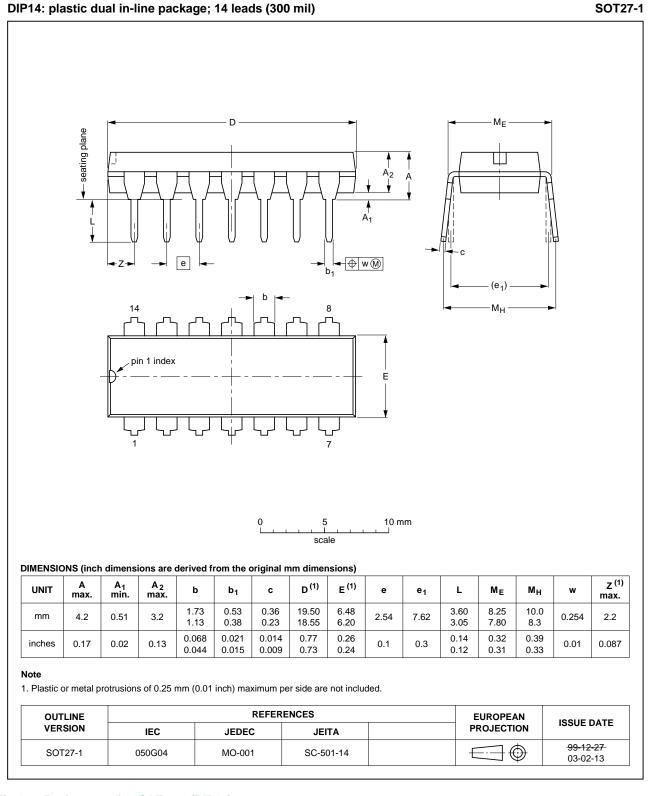
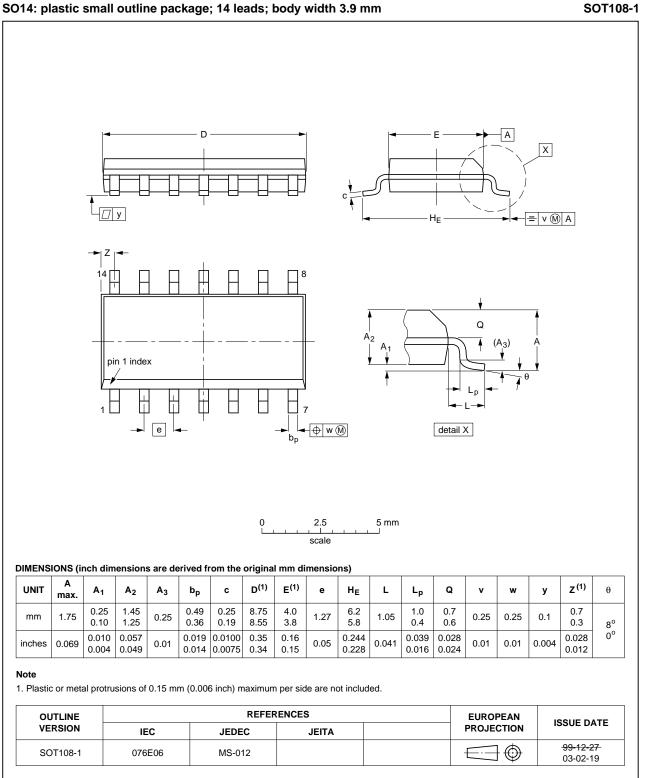


Fig 10. Package outline SOT27-1 (DIP14)

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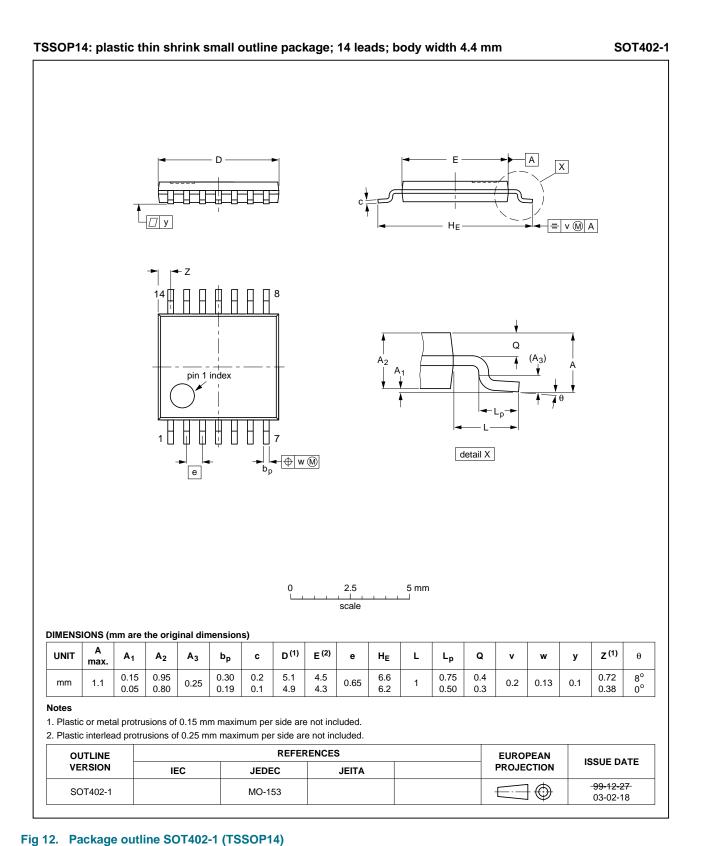
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SO14: plastic small outline package; 14 leads; body width 3.9 mm

Fig 11. Package outline SOT108-1 (SO14)



15. Revision history

Table 11. Revision histo Document ID	ory Release date	Data sheet status	Change notice	Supercodes
Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4013B v.7	20110913	Product data sheet	-	HEF4013B v.6
Modifications:	• <u>Table 6</u> : I _{OH}	minimum values changed to r	naximum	
HEF4013B v.6	20091027	Product data sheet	-	HEF4013B v.5
HEF4013B v.5	20090619	Product data sheet	-	HEF4013B v.4
HEF4013B v.4	20080515	Product data sheet	-	HEF4013B_CNV v.3
HEF4013B_CNV v.3	19950101	Product specification	-	HEF4013B_CNV v.2
HEF4013B_CNV v.2	19950101	Product specification	-	-

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Document status[1][2]	Product status ^[3]	Definition
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[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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